

K6D40 200N/5Nm/CG, 500N/20Nm/CG, 200N/5Nm/MP11, 500N/20Nm/MP11



Description

The K6D40 multi-component sensor is designed to measure the forces and torques on three mutually perpendicular axes.

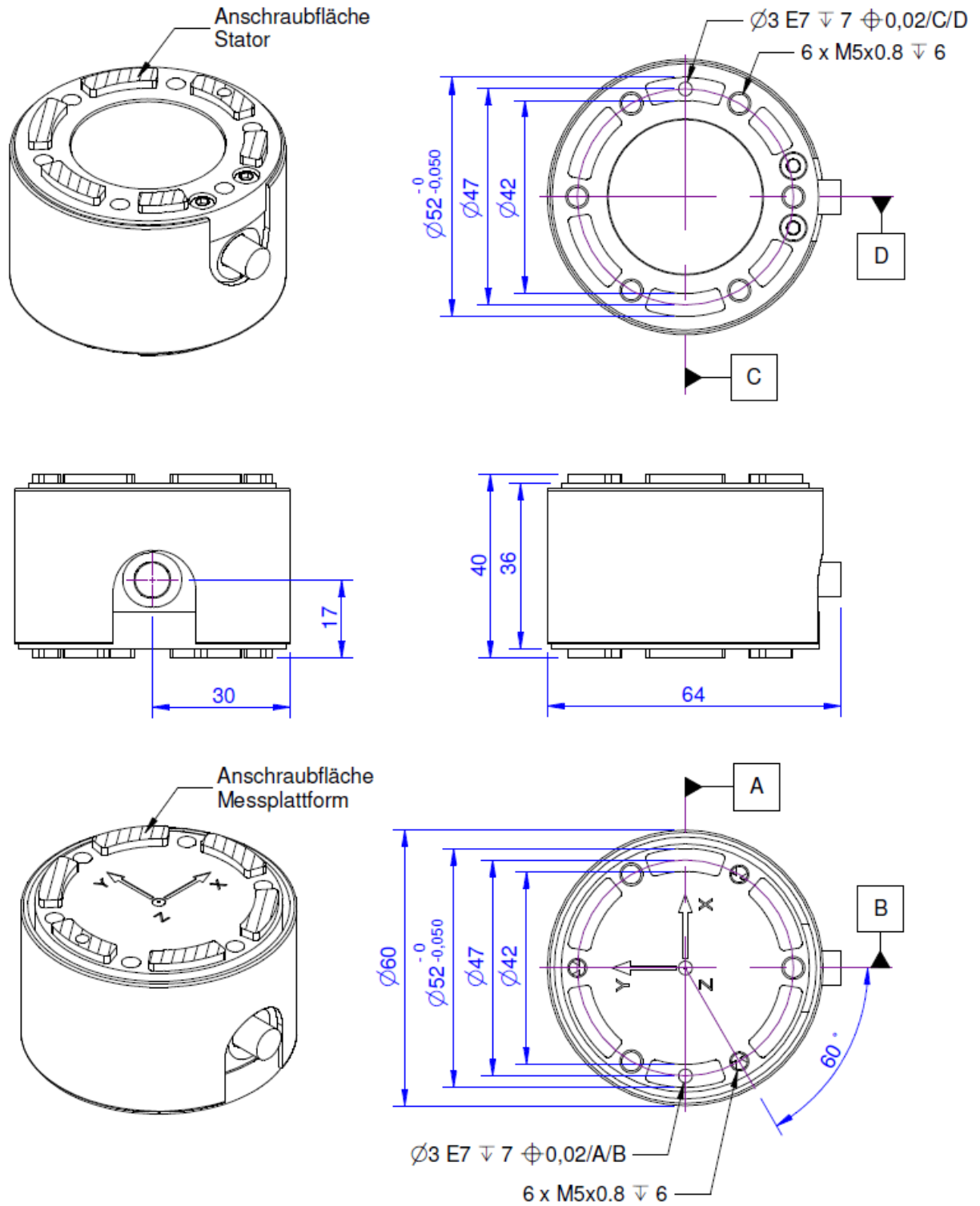
Owing to this sensor's very light weight of only 160 g (K6D40 200 N / 5 Nm) or 450 g (K6D40 500 N / 20 Nm), it is very well suited for use in robotics, e.g.

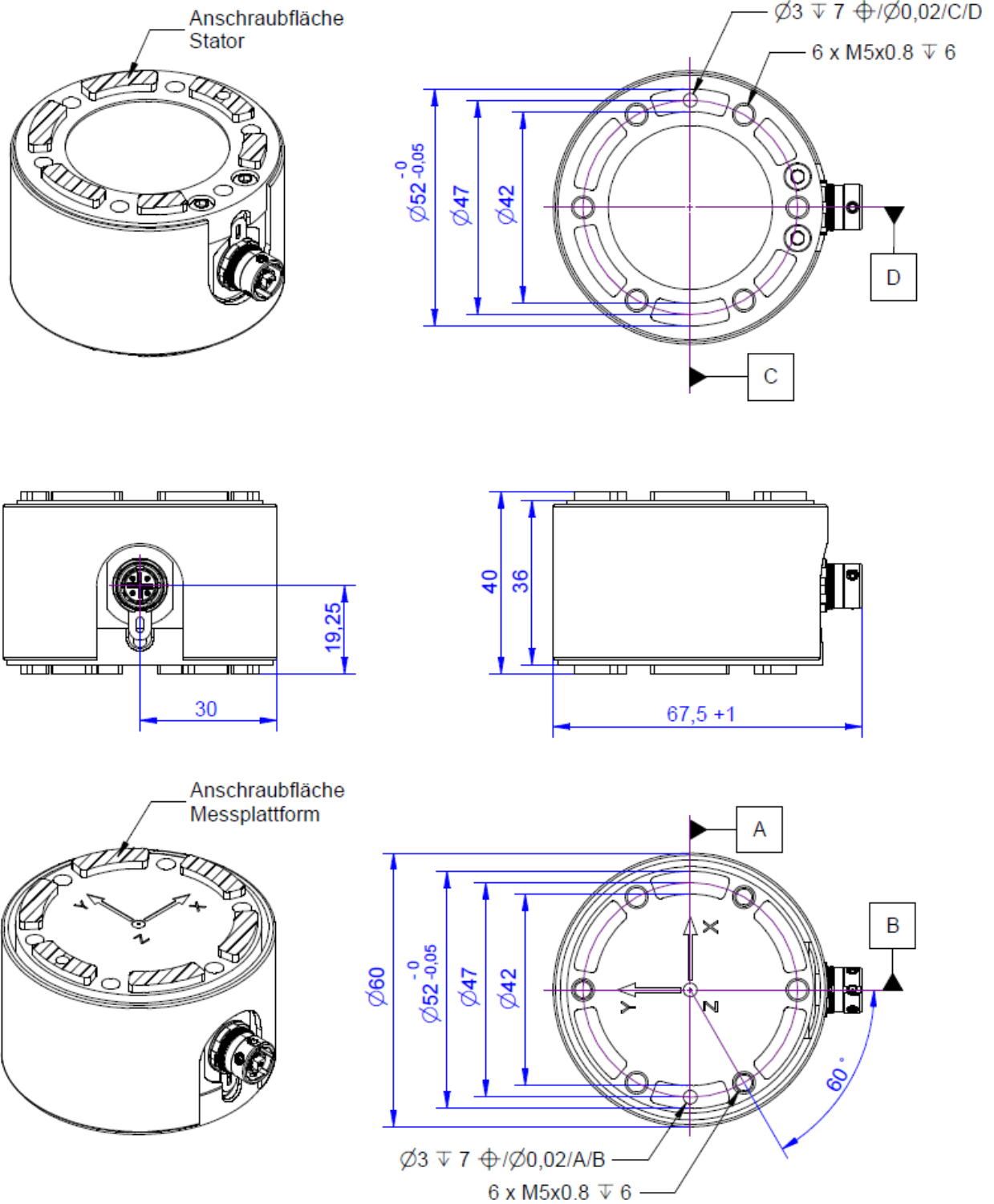
- For collision detection
- "Teach-In"
- Presence detection and error detection
- Force or torque-controlled operation
- Load measurement in medicine, prosthetics, orthopaedic engineering or gait analysis
- Measurement in sports medicine
- Comfort / ergonomics measurements

The force and torque loadings are evaluated e.g. using a GSV-1A8USB measurement amplifier. The 6 load values can be calculated using a Windows DLL or using LabVIEW with the aid of a digital calibration document provided. The calibration document contains the individual calibration factors and error corrections for the sensor.

The K6D40 200 N / 5 Nm sensor is made from aluminium alloy with a stainless steel housing. The K6D40 500N/20Nm sensor is made entirely of stainless steel.

Dimensions







Technical Data

Kraftsensoren

Type	6-Axis force sensor
Force direction	Tension / Compression
Force introduction	Inner thread
Dimension 1	6 x M5x0,8
Sensor Fastening	Inner thread
Dimension 2	6 x M5x0,8
Operating force	400 % FS
Material	Stainless steel
Dimensions	Ø60 x 40 mm
Height	40 mm
Length or Diameter	60 mm
Torque limit	300 % FS
Bending moment limit	500 % FS

Elektrische Daten

Input resistance	350 Ohm
Tolerance input resistance	10 Ohm
Output resistance	350 Ohm
Tolerance output resistance	10 Ohm
Insulation resistance	2 GOhm
Rated range of excitation voltage f	2.5 ... 5 V
Operating range of excitation voltage f	1 ... 5 V
nullsignalbereichMin	-1.5 mV/V
nullsignalbereichMax	1.5 mV/V

Precision

Relative linearity error	0.1 % FS
Relative zero signal hysteresis	0.1 % FS
Temperature effect on zero signal	0.1 % FS/K
Temperature effect on characteristic value	0.05 % RD/K
Relative creep	0.1 % FS
Relative repeatability error	0.5 % FS

Connection Data



Connection type	24 conductor open
Name of the connection	33-24 PUR/24x0,03 mm ²
Cable length	5 m

Temperature

Rated temperature range f	-10 ... 70 °C
Operating temperature range f	-10 ... 85 °C
Storage temperature range f	-10 ... 85 °C
Environmental protection	IP65

Abbreviation : RD: „Reading“; FS: „Full Scale“;

The application of a calibration matrix is required for the determination of the forces F_x , F_y , F_z and moments M_x , M_y , and M_z from the 6 measurement channels, and to compensate for the crosstalk.

The calibration data are individually determined and documented for the sensor.

The measurement error is expressed individually by the specification of the extended measurement uncertainty ($k = 2$) for the forces F_x , F_y , F_z , and moments M_x , M_y , M_z .



Pin Configuration

Channel	Symbol	Description	Wire colour	PIN
1	+Us	positive bridge supply	red	1
	-Us	negative bridge supply	black	2
	+Ud	positive bridge output	green	3
	-Ud	negative bridge output	white	4
2	+Us	positive bridge supply	blue	5
	-Us	negative bridge supply	yellow	6
	+Ud	positive bridge output	purple	7
	-Ud	negative bridge output	grey	8
3	+Us	positive bridge supply	orange	9
	-Us	negative bridge supply	brown	10
	+Ud	positive bridge output	pink	11
	-Ud	negative bridge output	transparent	12
4	+Us	positive bridge supply	green-black	13
	-Us	negative bridge supply	black-white	14
	+Ud	positive bridge output	red-black	15
	-Ud	negative bridge output	white-black	16
5	+Us	positive bridge supply	purple-black	17
	-Us	negative bridge supply	yellow-black	18
	+Ud	positive bridge output	blue-black	19
	-Ud	negative bridge output	gray-black	20
6	+Us	positive bridge supply	pink-black	21
	-Us	negative bridge supply	brown-black	22
	+Ud	positive bridge output	orange-black	23
	-Ud	negative bridge output	transparent-black	24

Shield: connected with sensor housing;



Manual

Stiffness Matrix K6D40 200N/5Nm

5.8 kN/mm	0.0	0.0	0.0	116 kN	0.0	u_x
0.0	5.8 kN/mm	0.0	-116 kN	0.0	0.0	u_y
0.0	0.0	32.3 kN/mm	0.0	0.0	0.0	u_z
0.0	-116 kN	0.0	9.3 kNm	0.0	0.0	ϕ_x
116 kN	0.0	0.0	0.0	9.3 kNm	0.0	ϕ_y
0.0	0.0	0.0	0.0	0.0	5.0 kNm	ϕ_z

Stiffness Matrix K6D40 500N/20Nm

15.9 kN/mm	0.0	0.0	0.0	319 kN	0.0	u_x
0.0	15.9 kN/mm	0.0	-319 kN	0.0	0.0	u_y
0.0	0.0	88.5 kN/mm	0.0	0.0	0.0	u_z
0.0	-319 kN	0.0	25.5 kNm	0.0	0.0	ϕ_x
319 kN	0.0	0.0	0.0	25.5 kNm	0.0	ϕ_y
0.0	0.0	0.0	0.0	0.0	13.8 kNm	ϕ_z

Element	Description
[kN/mm]	force-displacement
[kNm]	torque-twist
[kN]	force-twist and torque-displacement









Mounting

The force is applied to an annulus / to 6 segments of a circle, 52 mm – 42mm in diameter, on the end faces of the sensor. No force is applied to the area inside the ring with a diameter of 42 mm.

The areas outside the annuli can be used for centring purposes. A centring hole is provided to secure the angular position.

accessories

	Description	Description
	K6D- CalibrationMatrix SL	
	GSV-8AS	8-channel amplifier with USB port, analog output, UART interface. Other versions GSV-8AS CAN with Canbus and GSV-8AS EC with EtherCAT fieldbus.
	Configuration 24p/m/M16	Round plug, 24 pole, configured with sensor cable
	GSV-8DS	8-channel amplifier with USB port, analog output, UART interface. Other versions GSV-8AS CAN with Canbus and GSV-8AS EC with EtherCAT fieldbus.
	Configuration SubD44/m/HD	Connector Type SubD, 44 pins, male (male), with hood
	K6D-Adapter Development	Indicative offer for an adapter set, Consisting of e.g. 2 plates, For mounting a device / flange on K6D sensor;